





Using a modulation camera to control Pyramid Wavefront Sensor on the fly

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Towards a non-linear reconstructor ?



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 $s(\phi) = M_c \phi$

Pyramid WFS = Linear Parameter-Varying System (LPVS)

 $s(\phi) = M_{\phi}\phi$ Matrix which depends on ϕ

Interaction Matrix Space



The **Reconstructor** need to be aware of the state of the system We need to perform **gain scheduling**



 $I(\phi)$

How to perform gain scheduling ? One possible solution



Fauvarque 2019

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How to perform gain scheduling ? One possible solution





NO PAIN

ADVANTAGE: Absolute measurements « Free from the loop »

NO GAIN

BOOTSTRAP Open-Loop **Optical Gains** Fast Bootstrap Easier Bootstrap on strong turbulence Towards a non-modulated Pyramid ?

ENHANCEMENT OF CLOSED-LOOP ROBUSTNESS AND PERFORMANCE

Strong variation of seeing during the night



Seeing at Paranal October 21th 2019

HANDLING NCPA







Visible

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Because Optical Gains, the loop converge towards the wrong reference

Pushing too much !









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- Noise on modulation camera \longrightarrow Impact on Optical Gains computation ?
- Can we use the modulation camera at another wavelength ?





ANNEX: The Convolutional Model – FAUVARQUE 2019



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